

Mechanical Laboratory

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Date 31.08.2020

TEST REPORT NO. CBC-090/2020

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Subject of testing: Electric drive for a wheelchair

Classification according to

PN-EN ISO 9999:2017-02: 12 21 24

Type / Model:

PAWS

TOURER

SN.: (01)05907467803494

(11)200717(21)0001

Product Code: RPT20AAS00

Number of specimens: 1

Manufacturer:

REHASENSE Sp. z o.o..

ul. Sulejowska 45 G

97-300 Piotrków Trybunalski

Applicant:

A-Net s.c.

ul. Łaskowice174

93-469 Łódź.

Kind of testing

Testing scope according to application of Client

Mechanical testing for conformity with PN-EN 12184: 2014: PN-EN 12182:2012; ISO 7176-part 1, 2, 3, 4, 5, 6, 8, 9,10

Test started: 3.08.2020

Test finished: 31.08.2020

Approved by:

DYREKTOR kusons mgr inż. Andrzej Tkaczyk

Special comments / enclosures:

1) Annex 1-6 - Identyfication of wheelchair elements

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Test results refer only to tested units.

Test results reported here are not applicable to the further modifications of the product affecting its structure, material or technology. This test report shall be neither copied differently as in the whole nor be published without written consent of the Laboratory.



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CHARACTERISTIC OF ELECTRICALLY PROPELLED WHEELCHAIR

Name of wheelchair: PAWS Tourer SN (01)05907467803494(11)200717(21)0001

Maximum load capacity: 120 kg Overall mass of wheelchair: 41,71 kg Class: A

Electric drive for a wheelchair

Mass of the drive: 32,2 kg

Length of the drive: 1005 mm

Height of the drive: 955 mm

Wheel diameter: 569 mm

Wheel width: 99 mm

Wheel size: (100-406)20 x 4 Pressure: 30 PSI/200 kPa Material of the drive: alum., steel, plastic

	Descripti	Wheelchair	Wheelchair+ electric drive	
Dimensions:	Length:		778 mm	1490 mm
	Height (max.)		780 mm	1065 mm
	Width:		555 mm	555 mm
Construction of	Material:		Aluminum	Aluminum
frame:	Method of fastening	frame elements:	Welding/rivets/bolts	Welding/rivets/bol
	Folding/unfolding:		Unfolding	Unfolding
Drive wheels	Ø external:		533 mm	
	Ø pipe:		19 mm	
	Material:		Aluminum	
	Way of fastening to d	riven wheel	Bolts	
		points to driven wheel:	6	
Driving wheels	Material of ring of a		Aluminum	Aluminum
- · · · · · · · · · · · · · · · · · · ·	Dimension of tyre:	***************************************	24"x1"(25x540mm)	20x4(98x569mm)
	Pressure:		110 PSI,755 kPa, 7,5 bar	30 PSI, 200 kPa
	Way of fastening who	al to construction	Quick connector	Permanent
		number of fixing positions)	YES 3	NO NO
		nt (number of fixing positions):	YES 5	NO
	Inclination angle adju		NO NO	NO
	Inclination angle:	astment.	0,0"	NO.
Castor wheels	Ø of wheel:		98 mm	569 mm
Cabbot Wheels	Width:		34 mm	98 mm
	Material of ring of a	wheel.	Aluminum	Aluminum
	Material of fork:	WHOCK.	Aluminum	Steel
		number of fixing positions)	YES 3	No
		nt (number of fixing positions):	NO NO	NO
	Adjustment of axis in		YES	NO
Backrest	Folding/unfolding:	cimation angic:	Folding	Folding
	Backrest inclination	stepless:	NO	NO
	adjustment	number of fixing positions	4	4
Γilt levers	Two singular:		NO	NO
	One lateral:		NO	NO
Push handles	Kind:		One lateral	One lateral
Parking brake	Left:		YES	YES
	Right:		YES	
	Kind:		Lever	Disc brake
	Material of lever:		Plastic	Plastic
	Fastening to frame:		With screws	With screws
	Way of adjustment:		With screws and clamp stabilizing position of break towards tyre	
Upholstery	Material:		Nylon	Nylon
	Colour:		Black	Black



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egrests	Common for both legs:	YES
	Separate for each leg:	NO
	Stationary:	YES
	Folding:	NO
	Vertical adjustment (number of fixing positions)	YES
	Horizontal adjustment (number of fixing positions):	NO
	Angle adjustment (number of fixing positions):	NO
	Material of legrest:	Aluminum
ccessories	Seat belt	NO
	Anti-overturn device:	NO
	Anterior pelvic support:	YES
	Service:	YES
	PHOTO OF WHEELCHAIR	
12	km/h to t	



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TESTING

NORMATIVE REFERENCES	Applied
PN-EN 12182:2012 Technical aids for disabled persons - General requirements and test methods	YES
PN-EN 12183:2014 Manually propelled wheelchairs - Requirements and test methods	NO
PN-EN 12184:2014 Electrically powered wheelchairs, scooters and their chargers - Requirements and test method	YES
ISO 7176-1:2014 Wheelchairs - Determination of static stability	YES
ISO 7176-2:2001 Wheelchairs - Determination of dynamic stability of electric wheelchairs	YES
ISO 7176-3:2012 Wheelchairs - Determination of efficiency of brakes	YES
ISO 7176-4:2008 Wheelchairs – Energy consumption of electric wheelchairs and scooters and determination of theoretical distance	YES
ISO 7176-5:2008 Wheelchairs - Determination of overall dimensions, mass and turning space	YES
ISO 7176-6:2001 Wheelchairs – Determination of maximum speed, acceleration and retardation of electric wheelchairs	YES
PN-ISO 7176-7:2001 Wheelchairs - Measurement of seating and wheel dimensions	NO
ISO 7176-8:2014 Wheelchairs - Requirements and test methods for static, impact and fatigue strengths	YES
ISO 7176-9:2009 Wheelchairs – Climatic test for electric wheelchairs	YES
ISO 7176-10:2008 Wheelchairs - Determination of obstacle-climbing ability of electric wheelchairs	YES
PN-ISO 7176-14:2001 Wheelchairs – Power and control systems for electric wheelchairs – Requirements and test methods	NO
PN-ISO 7176-15: 2002 Wheelchairs - Requirements for informative disclosure, documentation and labelling	NO
PN-EN 1021-1:2007 Furniture. Assessment of ignitability o upholstered furniture. Ignition source: smouldering cigarette.	NO
PN-ISO 7176-16:2001 equivalent: PN-90/P-04823 Wheelchairs. Resistance to ignition of upholstered parts — Requirements and test methods	NO
ISO 7176-16:2012 Wheelchairs. Resistance to ignition of upholstered parts - Requirements and test methods	NO
PN-ISO 7176-19:2007 Wheelchairs. Wheeled mobility devices for use in motor vehicles	NO

RESULT OF MECHANICAL TESTS ACCORDING TO PN-EN 12182:2012

Requirement s according to classe	Test method according to clause	Checked characteristics/assemblies/parameters	Test result	Opinion	Comments
4.1	4.8, 5.2, 5.4.2, 5.5, 6, 8.2.1, 9.4, 10, 22, 24 and EN 1441	Risk analysis	-	N/T	
4.2	V/I	Expected characteristics and technical documentation	Conf.	Pos.	
4.3	EN ISO 14155	Clinic assessment	_	N/T	
4.4	V/I	Technical support which can be dismantled	Conf.	Pos.	
4.5	V/I	Single use connections	Conf.	Pos.	
4.6	V/I	Boundary values of user weight	Conf.	Pos.	
4.7	V/I	Immobilising means	Conf	Pos.	
4.8	V/I, C5	Suitability of the product for people with cognitive impairment	_	N/T	
4.0		The presence of the description in the manufacturer's documentation	_	N/T	
		Materials			
5.1	EN 60601-1-9	Recycling		N/T	
5.2	V/I, B 5.2	Flammability (PN-EN 1021-1:2007)	_	N/T	NOTE 9
5.2.2	V/I	Upholstered parts, mattresses, bed bases and bedding	_	N/A	
5.2.3	V/I, EN 1021	Upholstered parts	_	N/A	
5.2.4	V/I, EN 597	Mattresses and bed bases	_	N/A	
5.2.5	V/I. EN ISO 12952	Bedding	_	N/A	
5.2.6	V/I. EN 60695-11-10	Moulded parts	_	N/T	
5.3	EN ISO 10993-1 Annex. D	Biological conformity and toxicity	_	N/T	



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Requirements a according to clause	Test method according to clause		charac	Checked teristics/assemblies/par	ameters	Test result	Opinion		Comments
5.4	V/I	Cor	ntaminant	s and residues			N/A		
	V/L,B.5.	5.1 8 7	2 c	Cleaning		Conf.	Pos.	Comment	s in service manu
	V/L,B.5.5	5.1		Disinfection			N/A		
5.5	V/L, EN E 22442-1 B.5.5.2		i missuons and cochamination	Animal tissue		_	N/A		
5.6	EN ISO 92	227 Res	istance to	corrosion		-	N/T		
6		Em	itted sou	nd and vibration					
6.1	EN ISO 3'	746 Noi	ise and vi	bration		Conf.	Pos.		
6.2	EN ISO 3		md levels	and frequencies of audible w	arning	Conf.	Pos.		
6.3	EN ISO 37	746 Fee	edback			i - I	N/A		
7	EN 60601- 7.2, 7.3, 7	1-2 Ele		etic compatibility		_	N/T		
8	1.4, 1,3, 1		ctrical saf	etv			N/T		
9	V/I			illage, leakage, and ingress of	f liquids	_	N/A		
10	V/L Meas		face temp		•	-	N/A	f ≤41°C ■ requirement does not conce direct solar radiation - Pl 12182, clause 10a ■ requirement concerns only with insensitiveness of skin (w	
11	V/I	Ster	rility			_	N/A	Jees made -1	14-514 12102 CRIMS 1
12	V/L Meas	ur. Saf	ety of mo	ving parts		Conf.	Pos.	Comments	in service manua
13	V/L Meas	ur. Pre	vention of	f traps for parts of the human	body	Conf.	Pos.	Comments	in service manua
14	V/I	Fol	ding and a	adjusting mechanisms		Conf.	Pos.	Comments	in service manua
15	V/L Meas	ur. Car	rying han	dles		Conf.	Pos.	Comments	in service manue
16	V/L Meas			ducts which support or susper	nd users	Conf.	Pos.		re tested by O 7176-8:2014
17	V/I. Meas			mobile assistive products		Conf.	Pos.		re tested by O 7176-8:2014
18	V/I, B 1			ners, edges and protruding pa	rts	Conf.	Pos.		
19	B 19			sistive products		_	N/A		
20	B 20		all Parts			Conf.	Pos.		in service manu
21	V/I. Meast EN 60601		bility			Conf.	Pos.		re tested by 7176-1:2014
22	B 22, V/	I For	ces in sof	tissues of the human body		Conf.	Pos.		
23	V/L EN 614-		onomic p	rinciples		_	N/T		ements relate to the
		TE	ST RI	ESULTS ACCORD				2014	
Require ments ccordin g to clause	Test method according to clause	Che	ked ch	7 WHEELCHAIR 1 aracteristics/assemblies			est result	Opinio n	Comments
			charakte						
8.1.1 8.1.2	9122			rements of the table 1 and 2 ated slope	1100	TO 6	Conf.	Pos.	T-1 1 /-1 4 D- 10
	8.1.2.2			*	NOT	E O	3° Conf.	Pos.	Tab.1 (cl.A β≥3° Tab.1 (cl.B β≥6°
1.3.2	8.1.3.3		unevenne					N/A	3 support points
.1.4.1	8.1.4.2 8.1.5.2		m downh	THE STATE OF THE S			<u> </u>	N/A	$\leq 125\% V_{max}$ Tab.1 (cl.A $\beta \geq 3^{\circ}$)
.1.6.1	8.1.6.2		stability	and descending	NOTE	7.8	3° Conf.	Pos.	Tab.1 (cl.B $\beta \ge 6$) (cl.A h $\ge 15mm$)
	ISO7176-10	- combit			11011	13	mm Conf.	Pos.	$(cl.B h \ge 10mm)$



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Require ments accordin g to clause	Test method according to clause	Checked characteristics/assemblies/parameters	Test Opi result nion			Comments	
8.1.7.1	8,1,7,2 ISO7176-1	Static stability	Conf.	Pos.	Tab.	1 (cl.A)	(26°)
8.1.8.1	8.1.8.2 ISO7176-6	Maximum speed	Conf.	Pos.	2 000	Z (GILD)	
8.1.9.1	8.1.9.2 ISO7176-4	Distance range	Conf.	Pos.			
8.2.1	8.2.2 ISO7176-8	Static, impact and fatique strength	Conf.	Pos.			
8.3	ISO7176-19	Wheelchairs for use as seats in motor vehicles		N/T			
8.4	ISO7176-9	Climatic performance	Conf.	Pos.			
***	03.04	Component properties			****		
9.1.1	9.1.2.1	Foot supports, lower leg support assemblies and arm supports		-	NA		
		Possibility to position the occupant's feet at the required height Presence of the technical means to prevent the occupant's feet from sliding Foot supports, lower leg support assemblies and arm supports should:		-	N/A N/A		
		-Incorporate a means to locate it securely in any intended operating position		_	N/A		
		-Be adjustable in increments not exceeding 25mm		_	N/A		
		-Be accessible and operable by the occupant or an assistant or both in accordance we manufacturer's intended use of the wheelchair	th the	-	N/A		
		-Be within the reach space shown in Figure 1		-	N/A		
		-Be operable without the use of tools		-	N/A		
		-Means to prevent the occupant's feet from sliding into the gap shall be provided, or		-	N/A		
		-The gap between the footrests ≤35mm or ≥100mm for adults and ≤25mm or ≥45 children	mm for		N/A		
9.2	V/I Measur.	Component mass					
		Presence of the handling devices (e.g. handles) in components of mass greater than 10 kg, or	-	N/O	V/U dismant		a be
		Information indicating the points where components can be lifted and describing how they shall be handled during disassembly, lifting, carrying and assembly available	Conf.	Pos.	ma	ss of the h parts 32,2 k	eavies
9.3	V/I	Pneumatic tyres					
		Presence of the same type of valve connection on all tyres		Con	of. Po	S.	
		Valves should be readily accessible when using the intended inflating to		Col	uf. Po	S.	
		Presence of the marking of the tyres or the rims with the maximum presbar or PSI	sure in kPa	Col	_		
9.4		Anterior pelvic support					
9.5.1	EN 1021-1 EN 1021-2		NOTE 9		2.47		
9.5.2	ATLAUL FILE		NOTE 9		- N/		
9.5.3			NOTE 9		· N/		
9.5.4		Power and control systems		_ _	· N/	T	_
10		PROPULSION AND BRAKING	SYSTEN	1			
10.1.1	V/I Meas.				Conf.	Pos.	
		Means for operating brakes shall:					
		-be accessible and operable by the occupant or an assistant or both in accordance	e with the		Conf.	Pos.	
		manufacturer's intended use of the wheelchair -be within the reach space shown in Figure 1, if the wheelchair is intended to be	onerstad has	thė	_	-	
		occupant	oberater by	arc	Conf.	Pos.	
		-be within the reach space shown in Figure 3, if the wheelchair is intended to be an assistant			_	N/A	
		-have operating forces for engaging and disengaging that do not exceed those st tested in accordance with 10.1.2		1 when	Conf.	Pos.	
		If one or more brake levers are fitted to a wheelchair in the form used on b mopeds: -for wheelchairs with a maximum occupant mass not greater than 150 kg, the form the first state of the state of th		o each			
10.1.1	V/I	lever to hold the loaded wheelchair stationary on the rated slope shall not excee - for wheelchairs with a maximum occupant mass greater than 150 kg, the force	d 60 N applied to ea		Conf.	Pos.	
	Meas.	lever to hold the loaded wheelchair stationary on the rated slope should not excepthe handgrip width of such brake levers when no force is applied, measured 15	ed 60 N		Conf.	Pos.	00
		the brake lever, shall not be greater than 100 mm and should not be greater that 4).	n 80 mm (se	e Figure	Conf.	Pos.	90 mm
		 -Means for releasing parking brakes shall be protected against activation caused contact 	oy accidenti	11	Conf.	Pos.	

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10.2.1	10.2.2.1	Braking functions			
	10.2.2.2 10.2.2.3 10.2.2.4 ISO7176-3	a) The wheelchair shall have a running brake which operates independently of tyre wear and tyre inflation pressure and which does not exceed the maximum stopping distance specified in Table 2 when tested in accordance with 10.2.2,1.	Conf.	Pos.	
		b) The wheelchair shall have a running brake which, when operated after the wheelchair has been put into freewheel mode, shall bring the wheelchair to a stop	Conf.	Pos.	
		c) The wheelchair shall have an automatic brake, which operates independently of tyre wear and tyre inflation pressure and which is operated by releasing the control device to achieve a zero speed command (e.g. spring loaded disc brake)	_	N/T	
		d)The wheelchair shall have a parking brake which operates independently of tyre wear and tyre inflation pressure (e.g. drum brake in wheels, spring loaded disc brake)	Conf.	Pos.	
		e)Parking brakes shall meet the parking brake effectiveness requirement in Table 1 when tested in accordance with 10,2.2.2	Conf.	Pos.	
		f)Parking brakes shall be operable when there is no power from the battery supplying the drive system.	Conf.	Pos.	
		g)Parking brakes shall be operable when the wheelchair is in freewheel mode (see NOTE 1)	Conf.	Pos.	
		h)If they are subject to wear, parking brakes shall have provision for adjustment and/or replacement as specified by the manufacturer	Conf.	Pos.	
		i) If the wheelchair is fitted with arm supports that can be moved or removed to enable transfer, when tested in accordance with 10.2.2.3, engaged parking brakes shall not have parts that protrude above the level of the occupied seat	_	N/A	
		j)When parking brakes are tested in accordance with 10.2.2.4, no parking brake mechanism shall move from the pre-set position and no component or assembly of parts shall show visible signs of cracks, breakages, gross deformations, free play, loss of adjustment or any other damage that adversely affects the function of the wheelchair	Conf.	Pos.	
		k)Following testing of the parking brake in accordance with 10.2.2.4, parking brakes shall meet the parking brake effectiveness requirement in Table 1 when tested again in accordance with 10.2.2.2.	Conf.	Pos.	
10,3	V/I,Meas.				
		The wheelchair shall be fitted with a freewheel device that shall:		N/T	
		-be accessible and operable by the occupant or an assistant or both in accordance with the manufacturer's intended use of the wheelchair		NT	
		-be within the reach space shown in Figure 1, if the wheelchair is intended to be operated by the occupant	_	N/T	
		-be within the reach space shown in Figure 3, if the wheelchair is intended to be operated solely by an assistant	_	N/T	
		-have operating forces for engaging and disengaging that do not exceed those stated in Table 1	-	N/T	
		-be operable without detaching any parts	-	N/T	
		-not depend on the battery power supplying the motor drive system	_	N/T	
		-have two defined positions including clear indication of freewheel mode and drive mode	_	N/T	
		-prevent use of the wheelchair's drive system, if the freewheel device is activated.	l –	N/T	
11.1	V/I	Operations intended to be carried out by the occupant and/or assistant	Conf.	Pos.	
11.2	V/I	Controls intended for operation by the occupant	Conf.	Pos.	
11.3	V/I	Controls intended for operation by an assistant	-	N/A	
11.4.1	11.4,2	Assistant control unit, push handles and handgrips		N/A	
1.5.1	11.5.2	Operating forces	Conf.	Pos.	
11.6.1	11.6.2	Seating adjustments for tilt and recline systems NOTE: required warning and/or mechanism procluding seating adjustment while the occupant is seating	-	N/A	
		Controls for seating adjustments intended to be operated by the occupant shall be accessible to the occupant from all seating positions		N/A	
12		Electrical systems			
12.1	7176-14 7176-21 60601-1	General requirements	-	N/T	
12.2	V/I,Meas.	Circuit protection	-	N/T	
12.3	7176-14 EN 60529 EN60335-1	Battery chargers	_	N/T	
12.4	V/I	Charging connector	-	N/T	
12.5	V/I	Battery enclosures and containers	_	N/T	-
12.6	7176-14	Emergency stop	_	N/T	
12.7	2006/42/WE 76/756/EWG 97/28/WE	Lighting	_	N/T	
12.8	7176-14	Switching off while driving		NT	
12,9	EN62304	Software		NT	
				N/T	

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Require ments according to clause	Test method according to clause	Checked characteristics/assemblies/parameters	Page:	Opini on	Com
13	V/I	Information supplied by the manufacturer			
		Information and marking conforming EN 12182 available	_	NT	
		Information and marking conforming ISO7176-15 available	_	N/T	
	13.2	Pre-sale information available	_	NT	
	13.3	User information available	_	N/T	
		Service information available	_	N/T	
12184	V/I	Instructions for use			
13.3		Pre-sale Information			
		a)information on how to obtain the user information in a format appropriate for use by		N. COL	
		visually impaired people	_	NT	
		b)a description of the intended use and the intended environment	_	N/T	
		c)the intended operator (occupant, assistant or both)		N/T	
		d)a description of the intended use and the intended environment		N/T	
		e)the type class of the wheelchair: Class A, B or C		N/T	
		f)the overall dimensions (width, length and height) of the assistive product, expressed in millimetres, and its mass, expressed in kilograms, when it is ready for use and, if applicable, when it is folded or dismantled	_	N/T	
		g) if the overall dimensions of the wheelchair when it is ready for use exceed the values recommended in A.1.1, a clear statement that the wheelchair is larger than the recommended dimensions	-	N/T	
		h)the minimum width of corridor in which the wheelchair can be turned to face the opposite direction	-	N/T	
		i)the rated slope, expressed in degrees	-	N/T	
		j)the standard options that are available for the wheelchair	_	NT	
		k)the type(s) of tyres that can be used on the eheelchair		N/T	
		1)operator adjustments	_	N/T	
		m)the mass expressed in kilograms if the assistive product can be disman-tled or has any removable parts that has a mass which is heavier than 10 kg.	<u></u>	N/T	
	1	n)information concerning whether the removal of parts or accessories intended by the manufacturer to be removed without the use of tools will have adverse or beneficial effects on the wheelchair	_	N/T	
	,	o)information on whether or not the wheelchair is intended to be used as a seat in a motor vehicle, and whether and how this depends on the standard options referred to in j)	-	N/T	
_		p)instructions regarding transport of the assistive product (e.g. in a car or aeroplane)	_	N/T	
	,	q)the theoretical continous driving distance range, expressed in kilometres, that the wheelchair can travel under its own power on the horizontal when tested in accordance with ISO 7176-4:2008, with the addition of a note explaining that the distance will be reduced if the wheelchair is used frequently on slopes, rough ground or to climb kerbs, etc.	-	N/T	
	1	r)the maximum height of kerb which the wheelchair can descend safely	_	N/T	
		s)if a programmable controller is fitted, information on the method of programming, the competence required to carry out the programming and the effects on performance	-	N/T	
2184		User information			
13.3]	User information shall be provided by the manufacturer with each assistive product. Information shall contain all pre-sale warnings and informations and the following as applicable for each assistive product	-	N/T	
	1	a)the location and the type of identification number/word on the assistive product shall be given for the unique identification number of the assistive product	-	N/T	
	i	b) any adjustment or settings required before the assistive product can be used and information on how adjustments or settings affect the assistive product	_	N/T	
	1	c)information on adjustment possibilities and the competence required to carry out these adjustments	-	N/T	
_		i)instructions on operation of all controls, including brakes	-	N/T	
	f	e)instructions on how to engage and disengage the drive system Othe wheelchair manufacturer's recommended tyre pressure(s), expressed in kPa, bar, or	-	N/T N/T	
-		PSI	-		
)instructions for dealing with tyre punctures, where pneumatic tyres are fitted	_	N/T	
		1)the battery type and nominal vottage	-	N/T	
	1)instructions for battery maintenance CENTRE FOR TESTING AND CERTIFICATION MECH-TEST, 05-077 Warazawa - Wasola, ul. Klonowa 22		N/T	24.

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2184 13.3	V/I	j)instructions for operating the battery charger, including warnings regarding any potential safety hazards (e.g. a possibility of gas accumulating in the charging area);				
		k) if required by the risk analysis, instructions for fitting an additional emergency stop				
		device where the intended occupant has an impairment which could restrict their ability to operate one	_	NT		
		1)instructions on whether and how the wheelchair can be folded to assist in storage or transport	_	N/T		
		m)instructions on dismantting and re-assembly of the assistive product or any removable parts:	-	N/T		
		n)instructions regarding transport of the assistive product (e.g. in a car or aeroplane)	_	N/T		
		o)the masses of parts of the wheelchair that are expected to be handled during				
		dismantling, reassembly, or carrying		N/T		
		p)the positions of points where the component parts can be gripped for safe moving and handling and/or a method for handling during dismantling, assembly or carrying	-	N/T		
		q)if the manufacturer specifies that the wheelchair is intended for use as a seat in a motor vehicle, the method of attaching wheelchair tiedown and occupant restraints, and recommendations about suitable tiedown and restraint systems	_	NT		
		r) if the manufacturer specifies that the wheelchair is not intended for use in the motor vehicle, a warning to that effect, together with the symbol shown in Figure 7	_	N/T		
		s) instructions on how to obtain and fit the optional anterior pelvic support (see 9.4) if it is				
		not supplied with the wheelchair; t) the positions of points intended to carry additional loads (grocery basket, backpack	-	N/T		
		hook)	_	N/T		
		u) instructions for preparing the wheelchair for long-term storage (e.g. longer than four months) and for preparing it for use afterward	_	NT		
		v) a warning that the wheelchair might disturb the operation of devices in its environment that emit electromagnetic fields (e.g. alarm systems of shops, automatic doors, etc.);	-	N/T		
		w) a warning that the driving performance of the wheelchair can be influenced by electromagnetic fields (e.g. those emitted by portable telephones, electricity generators or high power sources)	-	N/T		
		x) a warning that the stopping distance on slopes can be significantly greater than on level ground	_	NT		
		y) a warning that surface temperatures can increase when exposed to external sources of heat (e.g. sunlight);	_	N/T		
		z)if the intended purpose of an assistive product cannot be met without a hazard due to moving parts such as squeezing, a warning and instructions on how to operate the assistive product safely	_	N/T		
		aa) a warning if driving characteristics can be adjusted outside the limits specified in Table 1 and Table 2	-	NT		
		bb) a warning if the adjustments of seating or wheel positions can be set outside safe limits		N/T		
		cc) if the overall width or overall length of the wheelchair when it is ready for use exceed the applicable values recommended in A. 1.1, a warning concerning access to emergency escape routes	-	N/T		
		dd) the level of resistance to ignition of materials and assemblies	_	N/T		
		ee) information on the recycling of used batteries and of the wheelchair	_	N/T		
		ff) if the characteristics of the wheelchair (including occupant as applicable) exceed the limits specified in Annex M of the Technical Specification for Interoperability relating to Accessibility for Persons with Reduced Mobility (PRM-TSI), a statement to that effect (see Annex D);	_	NT		
		gg) information on how to find out about product safety notices and product recalls, for example by ensuring the supplier has up-to-date contact information	_	N/T		
		hh) the expected service life of the wheelchair	-	N/T		
_		ii) the name and address of the manufacturer	_	N/T		
		jj) the name and address of the authorised representative, where the manufacturer does not have a registered place of business in the European Union	-	NT		
2184	V/I	Service information				
13.4		The service information shall contain all the pre-sale information, user information and instructions necessary for the maintenance, adjustment and repair of the assistive product and for the replacement of parts.	-	N/T		
		The service information shall contain all the pre-sale information and the user information.	_	NT		
		The service information shall be sufficiently detailed concerning preventive inspection, maintenance and calibration, including the frequency of such maintenance.	_	NT		
		and the state of t	_	5		

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12184 13.4	V/I	The :	pervice information shall provide information for the safe the maintenance necessary to ensure the continued safe use	performance of su of the assistive pro-	ıch	س ا	N/T
		Addi inspe	tionalty, the service information shall identify the parts on ction and maintenance shall be performed by service pers ds to be applied and details about the actual performance of	which preventive onnel, including th	ie .	-	NT
13.5	V/I	Labe					NICE
		- dev	ices for disengagement of the drive system, showing enga	oed and disensace	á	-	N/T
		posit	ons, including a warning that the drive system should be nor attempts to operate the wheelcha	re-engaged before	an	-	N/T
		for w positi (WT)	heelchairs where yhe intended use includes use as a seat is on of attachment points for wheelchair tie-down and occuDRS)	n a motor vehicle, pant restraint syst	the ems		N/T
		effect same	heelchairs not intended to be used as a seat in a motor veh i, including the symbol shown in fig. 7 with a diameter not location as the labelling required by ISO 7176-15:1996	t less than 15mm,	in the	-	N/T
		speci	ttery chargers that are not on-board chargers, information fied in clause 9 of ISO 7176-14:1997		etails	-	N/T
		for C	lass A wheelchairs not intended for use outdoors, a warning	*		- 1	N/T
_		,	TEST RESULTS according to I	SO 7176-1			
Require ments accordin g to clause	Test method according to clause		hecked characteristics/assemblies/parameter	Test result	Opinio	n	Commen
PN-EN 2184	10.		ic stability of wheelchair facing up to the slope kwards) – factory regulations *)	18 *	Pos.		
8.			ic stability of wheelchair positioned backwards up to the e - factory regulations *)	30 °	Pos.	Tab. 1 (cl.1	
	12.	slop		160	Pos.	Tabl (c)	
Meas	urements w	ere mo	ade in the wheelchair with factory regulations (photo)			- 6	
			TEST RESULTS according to I	SO 7176-2			
	Test						
ments ecordin g to	method according to clause		Checked characteristics/assemblies/para	meters	Test result	Opini on	Comm
ments ecordin g to	method according	Stal	rility during start and stop when wheelchair drives forward		result 5,2" Cl.A	on Pos.	Ťab.
ments eccordin g to clause 4.	method according to clause 7.1.	For	vility during start and stop when wheelchair drives forward the required to operate hand (or foot) steering mechanism	is up to the slope	result 5,2" Cl.A 14 N	Pos. Pos.	Ťab. Cl.A (B
ments eccordin g to clause 4.	method according to clause 7.1.	For	wility during start and stop when wheelchair drives forward the required to operate hand (or foot) steering mechanism wility of braking during drive forwards and backwards down	is up to the slope	7,2" Cl.A 14 N 6" Cl.B	Pos. Pos. Pos.	Tab. Cl.A (B. Cl.B (B.
ments eccordin g to clause 4.	method according to clause 7.1.	For	wility during start and stop when wheelchair drives forward the required to operate hand (or foot) steering mechanism wility of braking during drive forwards and backwards downlity during turning	is up to the slope	result 5,2" Cl.A 14 N	Pos. Pos.	Ťab. Cl.A (B
d.	method according to clause 7.1.	For	wility during start and stop when wheelchair drives forward the required to operate hand (or foot) steering mechanism wility of braking during drive forwards and backwards down	is up to the slope	7,2" Cl.A 14 N 6" Cl.B	Pos. Pos. Pos.	Tab. Cl.A (B. Cl.B (B.
ments ecordin g to clause 4. 4. 4. tequire meats ecordin g to	method according to clause 7.1. 7.2. 7.3. Test method according	Ford State State	wility during start and stop when wheelchair drives forward the required to operate hand (or foot) steering mechanism wility of braking during drive forwards and backwards downlity during turning	is up to the slope	7,2" Cl.A 14 N 6" Cl.B	Pos. Pos. Pos. Pos.	Tab. Cl.A (B. Cl.B (B.
ments ecordin g to clause 4. 4. 4. kequire ments ecordin	method according to clause 7.1. 7.2. 7.3. Test method according to clause 7.1, V/I Measur. FN-EN 12184	Ford State State	cility during start and stop when wheelchair drives forward required to operate hand (or foot) steering mechanism cility of braking during drive forwards and backwards down cility during turning TEST RESULTS according to Is Checked	is up to the slope on the slope SO 7176-3	7,2 ⁸ CLA 14 N 6 ⁸ CLB 6 ⁸ CLB	Pos. Pos. Pos. Pos.	Tab. CLA (B CLB (B NOT)
tequire ments coording to clause 4. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4.	method according to clause 7.1. 7.2. 7.3. Test method according to clause 7.1, V/I Measur. PN-EN 12184 10.2.2.2 Tab. 1	Ford State State	ce required to operate hand (or foot) steering mechanism bility of braking during drive forwards and backwards down bility during turning TEST RESULTS according to IS Checked Characteristics/assemblies/parameters Effectiveness of parking brake of wheelchair positioned forwards down the slope	Is up to the slope In the slope SO 7176-3 Test result Conf. 14,5° (Cl. B)	result 5,2" CLA 14 N 6" CLB 6" CLB Opin	Pos. Pos. Pos. Pos.	Tab. CLA (B CLB (B NOT) Comme
ments ccordin g to clause 4. 4. 4. 4. dequire ments ccordin g to clause N-EN 12184 0.2.1.e	method according to clause 7.1. 7.2. 7.3. Test method according to clause 7.1, V/I Measur. PN-EN 12184 10.2.2.2	Ford State State	ce required to operate hand (or foot) steering mechanism bility of braking during drive forwards and backwards down bility during turning TEST RESULTS according to Is Checked Checked Characteristics/assemblies/parameters Effectiveness of parking brake of wheelchair positioned forwards down the slope Effectiveness of parking brake of wheelchair positioned backwards down the slope	Is up to the slope In the slope SO 7176-3 Test result Conf. 14,5° (Cl. B)	result 5,2" CLA 14 N 6" CLB 6" CLB Opin	Pos. Pos. Pos.	Tab. CLA (B CLB (B NOT) Comme



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Require ments accordin g to clause	Test method according to clause	Check	ked	characteristics/assemblies/	parameters	Test result	Opinio n	Comme	
7.2.1.a	V/I Measur.	ike		king distance during drive with ma	aximum speed (Vmax=15km/h)	3,6 m	Pos.		
7.2.1.b	V/I Measur.	[E		king distance during drive backwa		0,58 m	NA		
	V/I Measur.	Serv		king distance of wheelchair during slope of 5°	ng drive forwards	4,5 m	N/A		
	V/I Measur.	Resistance long brakin	of ng d	braking system to increased tempouring drive forwards on horizontal	plane	Conf.	Pos		
	V/I Measur.	Automatic brake		Braking distance of wheelchair of maximum speed forwards on hor	izontal slope	_	NT		
7.2.3.b	V/I Measur.			Braking distance of wheelchair of maximum speed forwards on slop			NT		
				TEST RESULTS acco	rding to ISO 71	76-4			
26 (0.7	Test method according to clause	Check	æd	characteristics/assemblies/		Test result	Opinion	Comme	ents
PN-EN 12184 Tabl. 2	7	Theoretical	ė en	ergy range		30,1 km	Pos.		
NÖTE; Ran	ge wheelch	iir was tested tr	1 700	d conditions. The average range of 5 attem					
	-			TEST RESULTS acco	rding to ISO 71	76-5			
Test method according to clause		aracterist		Checked assemblies/parameters	Test result wheelchair	Wheelchair + electric drive	# \ R'IA	etric drive	Opinion
8.2	Overal	length of w	hee	lchair with legrest and footrest	778 mm	1490 nun	10	05 mm	N/R.
8.3	Overal				555 mm	555 mm		30 marie	N/R.
8.4	Height	of grips abo	ve 1	the ground	625 mm	600 mm		N/A	N/R.
8.5				ded wheelchair	790 mini	N/A	12	30 mm	N/R.
8.6				h of folded wheelchair	500 mm	N/A	49	95 mm	N/R.
8.7				ded wheelchair	410 mm	N/A	72	20 mm	N/R.
8.8	overtur	wheels lift h n device	eig	ht in the wheelchair with anti-	N/A	N/A		N/A	N/R.
8.9	Mass				9,51 kg	41,71 kg	3.	2,2 kg	N/R.
8.10		f the heavier	_	arts	7,02 kg	_		2,2 kg	N/R.
8.11		vidth (fig. 9)			877 mm	1200 mm		_	N/R.
8.12				d by spacing of walls	950 mm	1600 mm			N/R.
8.13		ter of the rot			1020 mm	2500 mm			N/R.
8.14		d clearance			200 mm	45 mm		_	N/R.
8.15				ed corridor (fig. 15)	700 mm	850 mm		-	N/R.
8.16 8.17				y depth (fig. 14) h for side opening (fig. 13)	820 mm	1490 mm			N/R.
				n for side opening (fig. 13) nd PN-ISO 7193 recommended max of	700 mm	1250 mm		me.	N/R.

According to PN-EN 12183 Annex. B and PN-ISO 7193 recommended max overall dimensions: length: 1200mm, width: 700mm, height: 1200mm

*) Electric drive for a wheelchair standing, supported on supports

TEST DESITIES according to 150, 7174.

Test method according to clause	Checked characteristics/assemblies/parameters	Test result	Opinion	Comments
7.1.	Maximum speed during drive forwards	15.0km/h	Pös.	
7.2.	Maximum speed during drive backwards	4.6 km/h	Pos.	
8.1.	Maximum acceleration	0,64 m/s2	N/R	
8.2.	Maximum deceleration	2,4 m/s2	Pos.	



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Test method according to clause	Checked characteristics/assemblies/parameters	Test result	Opinion	Comments
7.3.2.	Angle of seat plane	_	N/T	
7.3.3.	Effective depth of seat	_	N/T	
7.3.4.	Width of seat	_	N/T	
7.3.5.	Effective width of seat	_	N/T	
7.3.6.	Height of front edge of seat plane		NT	
7.3.7.	Angle of backrest		N/T	
7.3.8.	Height of backrest		·N/T	
7.3.9,	Width of backrest	_	NT	
7.3.10.	Moving forward of headrest	_	NT	
7.3.11.	Height of headrest over the seat		NT	
7.3.12.	Distance of footrest from seat		NT	
7.3.13.	Clearance of footrest		NT	
7.3.14.	Length of footrest	_	NT	
7.3.15.	Angle of footrest	444	NT	
7.3.16.	Angle of legrest		NT	
7.3.17.	Height of armrests	_	NT	
7.3.18.	Moving forward of armrests		NT	
7.3.19.	Length of armrests		NT	
7.3.20.	Width of armrests	_	NT	
7.3.21.	Angle of armrests		NT	
7.3.22.	Distance between armrests		NT	
7.3.23.	Position of the front of armrests	_	NT	
7.3.24.	Diameter of drive wheel	-	NT	
7.3.25.	Diameter of driving wheel	_	NT	
7.3.26.	Displacement of wheel axis horizontally	_	ΝT	
7.3.27.	Displacement of wheel axis vertically		NT	
7.3.28.	Diameter of castor/front wheel		N/T	

NOTE 1: Measurements were made in the wheelchair with factory regulations (photo), (refer to ISO 7176-5, PN-ISO 7176-7)
NOTE 2: Measurements were made hurdening the wheelchair with dummy RLG - refers to PN-ISO 7176-7

TROP DESTRUCT

Require ments accordin g to clause	Test method according to clause Checked characteristics/assemblies/parameters		Test result	Opinion	Comments
4.	8.4.	Armrest - resistance to forces acting downwards	_	NT	
4.	8.5.	Footrests - resistance to forces acting upwards		N/T	
4.	8.6.	Anti-tip levers		N/A	
4.	8.7.	Grips		N/A	
4.	8.8.	Armrest forces acting upwards		N/T	
4.	8.9.	Footrest - forces acting upwards	_	N/T	
4.	8.10.	Handle grips for pushing - load acting upwards	_	N/T	
4.	8.11.	Scooter steering handles: Resistance to forward forces	Conf.	Pos.	loading 2 x 450N
4.	8.12.	Scooter steering handles: Resistance to rearward forces	Conf.	Pos.	loading 2 x 450N
4.	8.13.	Scooter steering handles: Resistance to downward forces		Pos.	loading 952 N
4.	8.14.	Scooter steering handles: Resistance to upward forces	Conf	Pos.	loading 952 N
4.	9.3.	Backrest - impact strength		N/T	
4.	9.4.	Driving wheel - impact strength		N/A	
4.	9.5.	Castor/front wheel - impact strength	Conf.	Pos.	10kg pendulum impact
4.	9.6.3.	Footrest - side impact	_	N/T	
4,	9.6.4.	Footrest - in-line impact		N/T	
4.	9.7.1.	Upward impacts on anti-tip devices	_	N/A	
4.	9.7.2.	Forward or rearward impacts on anti-tip devices		N/A	
4.	9.7.3.	Lateral impacts on anti-tip devices		N/A	
4.	10.3.2.	Testing of manually propelled wheelchair on two-drum machine $h=6mm\rightarrow M \le 75kg$, $h=9mm\rightarrow 100kg \le M = 75kg$, $h=12mm\rightarrow M \ge 100kg$	-	N/A	
4.	10.3.3.	Measurement of initial current for electrically powered wheelchair	_	N/R	
4.	10.3.4,	Testing of electrically powered wheelchair on two-drum machine $h=6mm\rightarrow M\leq 75kg$, $h=9mm\rightarrow 100kg\leq M>75kg$, $h=12mm\rightarrow M>100kg$	Conf.	Pos.	200 000 of cycles with full loading of wheelchair (120kg)



Require ments accordin g to clause	Test method according					Page:	13 of 18	
4.	to clause	Ch	ecked characteristics/assemblies/parameters	Test result	Opinion		omments	
	10.4.	Drop to	esting	Conf.	Pos.	with	rops of wheelchair th full loading from height of 50mm	
4.	10.5,	Fatigue	test of manually operated parking brakes	Conf.	Pos.		on neight of 50m 000 cycles	
JWAGA:	Dla p. 9.5	- kại 0 :			-			
Require			TEST RESULTS according to ISO	7176 –9				
ments accordin g to clause	Test me accordii claus	ng to se	Checked characteristics/assemblies/parameters	Test result C		C	comments	
8	7.3		Water resistance	Conf.	Pos.			
Damies		-	TEST RESULTS according to ISO 7176 -	10 (NO	TE 8)			
Require inents accordin g to clause	Test meth according clause	Checked characteristics/assemblies/parameters				t Opi lt nion		
PN-EN 2184:20 14	7.1.		ving forward when the wheels contact an obstacle ive onto an obstacle)		Conf.	cLA Pos.		
Tab. 2	7.2.		ving forward from a distance of 500mm from the ob- ive onto an obstacle)	stacle	Conf.	cl.A Pos.		
	7.3.	(dri	ving backwards when the wheels contact an obstacle ive onto an obstacle)	Conf.	cl.A Pos.	Tab. 1 (cl.A h≥15mm		
			ving backwards from a distance of 500mm from ive onto an obstacle)	le Conf.	A Pos.	(cl.B h≥50mn		
		(do	ling off an obstacle while driving forward wnhill from an obstacle)		Conf.	A Pos.		
	7.6.	Dri	ving backwards from an obstacle (downhill from an		Conf. c	LA Pos.		
l a andreas	70.4	43. 3	TEST RESULTS according to PN-ISO	7176 -1	4			
tequirem ents eccording to clause	Test m	ling to	Checked characteristics/assemblies/parame	ters Test	result	on	Comments	
	esting con	cerns el	ectrically propeller wheelchairs – performed by Electrotec	hnical Labo	ratory			
			TEST RESULTS according to PN-ISC					
	Test method according to clause		Checked characteristics/assemblies/parame	eters	Test resul		Comments	
.3		-	nt of service manual					
З.а	V/I		ncerning guarantee			N/T		
.3.b	V/I		ll characteristics: ption of wheelchair with photos or drawings and description	6 191		I		
		- descri	ption of user with maximum mass stated	ion —	N/T N/T			
			ption of environment of intended utilization		T	N/T		
			of recommended pressure in pneumatic tyres			NT		
.3.e	V/I	When v	wheelchair is sold in elements for individual assembly					
			components		_	N/T N/T		
		- inetra	- information on tools necessary to fold wheelchair - instruction of bringing lacking or damaged parts					
		- assem	bly, installation and disassembly instruction of parts delive	-	N/T N/T			
			tions for preparing wheelchair to storage, transport		_	N/T		
					N			
3.d	V/I	Service	manual of wheelchair		-			
3.d	V/I	Service - use of	manual of wheelchair wheelchair on surfaces where user moves		Ĭ -	N/T		
3.d	V/I	Service - use of - get on	manual of wheelchair wheelchair on surfaces where user moves and get off wheelchair			N/T		
3.d	V/I	Service - use of - get on - illustra	manual of wheelchair wheelchair on surfaces where user moves					

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Require ments accordin g to clause	Test method according to clause	Checked characteristics/assemblies/parameters	Test resul t	Op	fn ,	Comments
7.3.e	V/I	Maintenance instruction				
		 Details of maintenance: service, maintenance/detection of damages, for which user is responsible tools necessary for repair and service of wheelchair 	Ξ	N/		
		 maintenance frequency list of parts (with numbers) and way of is purchase conditions when manufacturer, supplier takes action 	_	N/	T T	
	-	Ways of cleaning	-	N/		
	1	Elements intended to easy replacement:	1-	147.		
		- information on orders	_	N/	r	
		- instruction of disassembly	- 1	N/		
		- information on replacement and testing of parts - illustration of parts and their placement	-	N/		
		Ways of performance dangerous activities	_	N/		
7.3.f	V/I	Performing of parameters control	=	N/	_	
Require ments	Test method according to clause	Checked characteristics/assemblies/parameters		est sult	Opi nion	Comment
7.3.g	V/I	Repair of wheelchair				
		- Identification of parts to be repaired by user	T.	_	N/T	
		- Identification of parts operated by manufacturer or service to maintain guarantee		_	NT	
		- Identification of parts removable and sent to manufacturer/service		-	N/T	
		- Conditions under which manufacturer/service is obliged to perform repair	1	_	N/T	
		- List of authorized service workshops	1	_	N/T	
		- Information if spare parts can be purchased			N/T	
		- Way of package and transport, if necessary	1	_	N/T	
Requirements according to clause	lg memo	Checked characteristics/assemblies/parameters		est suit	Opin ion	Commen
		Content of specification sheets of manufacturer	- 1			
Annex A		Content of specification sheets of manufacturer Manufacturer	1	- 1	NT	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address	1.	-	N/T	
Annex A Annex A	V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model		_	N/T N/T	
Annex A Annex A Annex A	V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user		-	N/T N/T N/T	
Annex A Annex A Annex A Annex A	V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest			N/T N/T N/T N/T	
Annex A Annex A Annex A Annex A Annex A	V/I V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width		-	N/T N/T N/T N/T	
Annex A Annex A Annex A Annex A Annex A	V/I V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly		-	N/T N/T N/T N/T N/T	
Annex A	V/I V/I V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly		-	N/T N/T N/T N/T N/T N/T	
Annex A	V/I V/I V/I V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly		-	N/T N/T N/T N/T N/T N/T N/T N/T	
Annex A	V/I V/I V/I V/I V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass		-	N/T N/T N/T N/T N/T N/T N/T N/T	
Annex A	V/I V/I V/I V/I V/I V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part		-	N/T	
Annex A	V/I V/I V/I V/I V/I V/I V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill		-	N/I	
Annex A	V/I V/I V/I V/I V/I V/I V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill		-	N/T	
Annex A	V/I V/I V/I V/I V/I V/I V/I V/I V/I V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability		-	N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability Energy range			N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability		-	N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability uphill Determination of obstacles			N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability uphill Determination of obstacles Maximum speed forward		-	N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability uphill Determination of obstacles			N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability uphill Determination of obstacles Maximum speed forward Minimum braking distance at maximum speed			N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability Energy range Dynamic stability uphill Determination of obstacles Maximum speed forward Minimum braking distance at maximum speed Seat plane angle			N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability uphill Determination of obstacles Maximum speed forward Minimum braking distance at maximum speed Seat plane angle Effective depth of seat			N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability Energy range Dynamic stability uphill Determination of obstacles Maximum speed forward Minimum braking distance at maximum speed Seat plane angle Effective depth of seat Effective width of seat			N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability Energy range Dynamic stability uphill Determination of obstacles Maximum speed forward Minimum braking distance at maximum speed Seat plane angle Effective depth of seat Effective width of seat Height of seat to front edge			N/T	
Annex A	V/I	Content of specification sheets of manufacturer Manufacturer Address Model Maximum mass of user Overall length with legrest Overall width Length after assembly Width after assembly Height after assembly Total mass Mass of the heaviest part Static stability downhill Static stability uphill Side static stability Energy range Dynamic stability uphill Determination of obstacles Maximum speed forward Minimum braking distance at maximum speed Seat plane angle Effective depth of seat Effective width of seat Height of seat to front edge Backrest angle			N/T	

Mechan	ical Lab	oratory of CBC Report	Report no.: CBC-090/2020 Page: 15 of 18				
Requirements according to clause	Test method according to clause	Checked characteristics/assemblies/parameters	Test result	Opin ion	Comments		
Annex A	V/I	Height of armrest from seat	_	N/T			
Annex A	V/I	Distance of front part of armrest from rear rest		NT			
Annex A	V/I	Diameter of drive wheel		N/T			
Annex A	V/I	Position of wheel axis horizontally		NT			
Annex A	V/I	Width of turning		NT			

Pos. - positive; Neg - negative; N/T - not tested; N/A - not applicable; N/R - not required , N/O - not occurred , V/L- visual inspection, Conf.- conformed.

- NOTE 1: During visual inspection before testing any visible defects that can have an effect on test results were not stated.
- NOTE 2: Sample/object for testing was delivered to the Laboratory by the Orderer.
- NOTE 3: Test dummy of mass 120 kg and person of required mass were used for testing.
- NOTE 4: Environment temperature for testing 19°C.
- NOTE 6: A loaded wheelchair (120kg) on a ramp with a slope 30, after driving a road of 5m uphill, it obtained a speed of 4,5 km/h (minimum 2 km/h required). Positive test result.
- NOTE 7: For class A wheelchair, dynamic stability was tested on a ramp with an incline of 30.
 - Dynamic stability in forward hill starts. Positive test result.
 - Dynamic stability when braking forward when going uphill. Positive test result.
 - Dynamic stability when braking forward when driving downhill. Positive test result.
 - Dynamic stability when braking backwards when driving downhill. Positive test result.
 - Dynamic stability when turning when driving on a ramp 3°. Positive test result.
- NOTE 8: For class B wheelchair, the ability to negotiate obstacles with a height of 50mm was tested. (according to ISO 7176-10)
 - cl. 7.1. Driving forward when the wheels contact an obstacle (drive onto an obstacle 50mm). Negative test result.
 - cl. 7.2 Driving forward from a distance of 500mm from the obstacle (drive onto an obstacle 50mm).

 Positive test result.
 - cl. 7.3. Driving backwards when the wheels contact an obstacle. (drive onto an obstacle 50mm).

 Negative test result.
 - cl. 7.4. Driving backwards from a distance of 500mm from the obstacle (drive onto an obstacle 50mm). Negative test result.
 - cl. 7.5. Riding off an obstacle while driving forward (downhill from an obstacle 50mm).

 Positive test result.
 - cl. 7.6. Driving backwards from an obstacle (downhill from an obstacle 50mm).
 Positive test result.

The tests were repeated for a class A wheelchair.

For class A wheelchair, the ability to negotiate obstacles with a height of 15mm was tested. (according to ISO 7176-10)

- cl. 7.1 Driving forward when the wheels contact an obstacle (drive onto an obstacle 15mm).

 Positive test result.
- cl. 7.2 Driving forward from a distance of 500mm from the obstacle (drive onto an obstacle 15mm).

 Positive test result.
- cl. 7.3 Driving backwards when the wheels contact an obstacle (drive onto an obstacle 15mm).

 Positive test result.
- cl. 7.4 Driving backwards from a distance of 500mm from the obstacle (drive onto an obstacle 15mm).

 Positive test result.
- cl. 7.5 Riding off an obstacle while driving forward (downhill from an obstacle 15mm).

 Positive test result.
- cl. 7.6 Driving backwards from an obstacle (downhill from an obstacle 15mm).

 Positive test result.
- NOTE 9: The wheelchair drive is not equipped with a seat (fabric + filling).



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	Final a	ssessment	
PN-EN 12182:2012	Pos.	ISO 7176-8:2014	Pos.
PN-EN 12183:2014	N/A	ISO 7176-9:2009	Pos.
PN-EN 12184:2014	Pos.	ISO 7176-10:2008	Pos.
ISO 7176-1:2014	Pos.	PN-ISO 7176-14:2001	NT
ISO 7176-2:2001	Pos.	PN-ISO 7176-15: 2002	N/T
ISO 7176-3:2012	Pos.	PN-EN 1021-1:2007	N/T
ISO 7176-4:2008	Pos.	PN-ISO 7176-16:2001	N/T
ISO 7176-5:2008	Tested*	ISO 7176-16:2012	N/T
ISO 7176-6:2001	Pos.	PN-ISO 7176-19:2007	N/T
PN-ISO 7176-7:2001	N/T		

^{*)} The standard does not specify requirements towards tested parameters of product

Note: Conformity assessment of product according to standard requirements refer to the scope of mechanical tests ordered by client, excluding testing of material biocompatibility with human body according to PN-EN ISO 10993-1:2010



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PN-EN 12184:2014 - Tab. 1 Requirements and tests for driving characteristics of type classes

Driving characteristics	Test		ıt	Test result Opinion		
		A	В	C		
Rated slope	8.1.2.2	min. 3°	min. 6 ⁸	min.10°	Cl. A	
Dynamic stability	8.1.5.2					
- starting forwards uphill		min. 3	min. 6°	min.10°	CL A	
- stopping forwards uphill		min. 3 ⁰	min. 6°	min.10°	CL A	
- stopping forwards downhill		min. 3	min. 6	min.10°	CL A	
 stopping backwards downhill 		min. 3	min. 6°	min.10	CL A	
Static stability	8.1.7.2					
- all directions		min. 6 ⁰	min. 9°	min.15°	CL C	
Maximum operating forces						
Brake levers	10.1.2					
Freewheel lever and controls	11.5.2					
 single finger operation 		5 N	5 N	5 N		
- more than one finger operation		13,5 N	13,5 N	13.5 N		
- whole hand operation		60 N	60 N	60 N		
- combined hand and arm operation		60 N	60 N	60 N		
 foot operation, pushing operation 		100 N	100 N	100 N		
 foot operation, pulling operation 		60 N	60 N	60 N		
Parking brake effectiveness	10.2.2.2	60	90	150	CL A	
Maximum speed	8.1.8					
- forwards horizontal		15 km/h	15 km/h	15 km/h		
- reverse horizontal		70%V _{max} or 5 km/h	70%V _{max} or 5 km/h	70%V _{max} or 5 km/h		
Obstacle climbing and descending ability	8.1.6.2	15 mm	50 mm	100 mm	CL A	
Continuose driving distance range	8.1.9,2	15 km	25 km	35 km	Cl. B	
Ground unevenness	8.1.3.3	10 mm	30 mm	50 mm	N/A	

PN-EN 12184:2014 Tab. 2 (cl. 10.2.2.2) Requirements and tests for driving characteristics on the horizontal for all type classess

Driving characteristics and rec	uirer	nents									T	est
The maximum value of the delay lastin	g longe	r than a	a 0,03	s = 4m	/s²:	2	,4ma/s ²	(Pos.)		PN-	ISO 717	76-6
Maximum stopping distance (ot Vma	x=15,0	km/h)				3	,6ш (Pos.)		PN	I-ISO 7	176-6
Speed (km/h):	4,0	5,0	6,0	7.0	8.0	9,0	10.0	11.0	12,0	13.0	14,0	15,0
Requiredbraking distance max.(m)	0,6	0,8	1,0	1,2	1,5	1.8	2.1	2,5	2,9	3.4	3,9	4,5
The actual value of the braking distance (m)	0,50	0,65	0,85	1,10	1,30	1,55	1,80	2,15	2,50	2,80	3,20	3,60

NOTE:

After the measurements of braking the wheelchair PAWS TOURER found that it meets the requirements of PN-EN 12184: 2014



MARKING VERIFICATION

Name of product: Electric drive for a wheelchair

PAWS TOURER

Manufacturer:

REHASENSE Sp. z o.o.. ul. Sulejowska 45 G

97-300 Piotrków Trybunalski

	rement according to PN-ISO 7176-15:2002	Durable marking on wheelchair
8.1.a	Name and address of manufacturer	N/T
8.1.b	Identification of model and serial number	N/T
8.1.c	Year of production	N/T
8.1.d	Information on likely driver constraints	N/T
8.1.e	Maximum mass of user	N/T
8.2	Marking of dimension on tyres	N/T
	rement according to PN-EN 12184:2014	Durable marking on wheelchair
13.5	Compatibility with EN 12182 and ISO 7176-15	N/T
	- devices for disengagement of the drive system, showing engaged and disengaged positions, including a warning that the drive system should be re-engaged before an occupant is left unattended or attempts to operate the wheelchair	N/T
	for wheelchairs where yhe intended use includes use as a seat in a motor vehicle, the position of attachment points for wheelchair tie-down and occupant restraint systems (WTORS)	N/T
	for wheelchairs not intended to be used as a seat in a motor vehicle, a warning to that effect, including the symbol shown in fig. 7 with a diameter not less than 15mm, in the same location as the labelling required by ISO 7176-15:1996	N/T
	for battery chargers that are not on-board chargers, information and connection details specified in clause 9 of ISO 7176-14:1997	N/T
	for Class A wheelchairs not intended for use outdoors, a warning to that effect	N/T
	CE marking not applicable	N/T

N/A – not applicable



Mechanical Laboratory

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ANNEX 1 TO TEST REPORT No. CBC-090/2020

Identification of wheelchair elements















Mechanical Laboratory

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ANNEX 2 TO TEST REPORT No. CBC-090/2020

identification of wheelchair elements















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ANNEX 3 TO TEST REPORT No. CBC-090/2020

Identification of wheelchair elements













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ANNEX 4 TO TEST REPORT No. CBC-090/2020

identification of wheelchair elements





E-bike li-ion battery

WARNING

- Do not short circuit positive and negative of the battery
 Do not dismantle the battery
 Do not place the battery under high temperature, such as heat, sunshine, or close to fire
 Do not place the battery in fluids, such as water, acid, alkaline or salt water
 If stored for a long time, keep the battery cool and dry, and charge the battery for 2 hours every other 3 months
- Always charge the battery with licensed charger for lithium ion or lithium polymer battery.

ZZ991304 48V11.8Ah(558.8Wh)







: 25%.Max 2Min ON/SMIn OFF

: Push1000N



MADE IN CHINA

Part No. TA2-1337-001

Spec code: TA2-2L-040165-2511-0A3-3

WARNING!

Using/driving the e-bike over speed is 100% on your own responsibility and the manufacturer will deny/refuse any responsibility of serious or damages to third party.





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ANNEX 5 TO TEST REPORT No. CBC-090/2020

Specification

Best Ebike Specification List

	City - 12" Wheel	Cruiser -16" Wheel	Tourer - 20" Wheel
Overall Dimension:(MM)(LxWxH)	800x490x810	820x490x860	1000x520x920
Packing Dimension:(MM)(LxWxH)	1100x550x260	1100x550x260	1200v850v300
Max weight of person:(KG)	120kg	120kg	120kg
Max. permissible overall weight (KG)	140.8kg	143.8kg	148.8kg
Total weight without battery pack:(KG)	17.5kg	20.5kg	125.5kg
Battery Weight:(KG)	3.3kg	3.3kg	3.3kg
Total weight :(KG)	20.8kg	23.8kg	28.8kg
Motor Power:(W)	350w	500w	550w
Motor Voltage:(V)	48v	48v	48v
Reverse Gear	Yes	Yes	Yes
Sattery Capacity:(Ah)	11.6Ah	11.6Ah	11,6Ah
Battery Rated Energy:(Wh)	557Wh	557Wh	557Wh
Battery Dimension:(MM)(LxWxH)	371X130X86	371X130X86	371X130X86
Battery Charger	Yes	Yes	YES
Charge time:(Hour)	5h	5h .	5h
Manual or Auto Operation	Option	Option	Option
Brake Solution	.Disk brake + E brake	Disk brake + E brake	Disk brake + E brake
Parking Brake	Yes:	Yes	Yes
Furning Radius:(M)	1m	1.2m	1.5m
Climbing capability up to	10 degree	10 degree	10 degree
Max Overriding Height	Somm	40mm	55mm
Range On flat terrian:(Km)	40km	38km	35km
Max Speed:(Km/h)	28km/h	28km/h	32km/h
Orive Mode:(Km/h)	5 modes(10,15,20,25,28)	5 modes(10,15,20,25,28)	5 modes(10,15,20,25,32)
Cruise Control	Yes	Yes	Yes
Valking Mode	Yes	Yes	Yes
Tetra Function	Option	Option	Option
rame Material	Steel and aluminum	Steel and aluminum	Steel and aluminum
Tire:(Inch)	12-1/2 x2-1/4 (57-203)	16 x 3.0 (76-305)	20 x4.0 (100-406)
Suggested Tire Pressure:(Bar)	2.8BAR	2.4-3.1BAR	2.0BAR
Rim	24 X 203	50 X305	73 X406
Sell or Horn	Hom	Harn	Hom
ront Light	Yes	Yes	Yes
Sasket	WA	N/A	Yes
nstalling Requirements of Wheelchair Seat Width Range)	Possitivity of covering all se	at width range,ready for custon	nizing as well.
nstalling Requirements of Wheelchair Seat Height Range)	Possibility of covering all se	at height range, ready for custor	mizing as well.





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ANNEX 6 TO TEST REPORT No. CBC-090/2020

Product configuration

PAWS TOURER product number: RPT20AAS00

PAWS
TOURER 20"
AUTOMATIC CLAMP & LIFT
Fat tyre 20"x 4" –
Lifter and automatic clamp
standard steering rods

